

Gradient flows, iterated logarithms, and semistability

Pranav Pandit

joint work with Fabian Haiden, Ludmil Katzarkov,
and Maxim Kontsevich

University of Vienna

June 7, 2018

This talk is based on:

- arXiv:1706.01073
- arXiv:1802.04123

Goals:

- Describe the asymptotic behavior of the flows discussed in the previous talk (in special cases)
- Describe a canonical refinement of the Harder-Narasimhan filtration, and its relation to the asymptotic behavior of the flow

Category	$\text{Fuk}(X, \omega)$	$\text{Rep}(Q)$
Object	Lag upto isotopy	$(\{E_\nu\}_\nu, \{T_\alpha\}_{\alpha \in \text{Arr}(Q)})$
Metrized object	Lagrangian	(E_ν, h_ν) , h_ν hermitian metric
Kähler data	Ω hol vol form	$P := \sum z_\nu p_\nu + \sum [T_\alpha^*, T_\alpha]$ $z_\nu \in \mathbb{H}; \nu \in Q_0$
Flow \mathcal{F}	$\dot{L} = \text{Arg} \Omega_L$	$h^{-1} \dot{h} = \text{Arg} P$
Mass M	$M(L) = \int_L \Omega $	$M = P $
Central charge	$Z(L) = \int_L \Omega$	$Z = \sum z_\nu \chi(E_\nu)$
Kähler potential	$dS_{\mathbb{C}}(f) = \int_L \Omega f$	$S_{\mathbb{C}} = \sum \log \det h_\nu + \sum T_\alpha^* T_\alpha$
Harmonic metric	Fixed points of \mathcal{F} $= \text{Crit}(S_{\mathbb{C}})$ $=$ special Lagrangian	Fixed points of \mathcal{F} /rescaling $= \text{Crit}(S_{\mathbb{C}})$
Amplitude	$\sup / \inf \text{Arg} \Omega _L$	$\sup / \inf \text{Spec Arg } P$
DUY theorem	??	King's theorem

Good features (some proven): (i) Mass, Amp decrease with flow; (ii) BPS inequality $|Z| \leq M$ and (iii) “properness” of mass.

Recall:

- There is a flow on the space of “metrized objects”.
- Fixed points of the flow on metrics upto rescaling are harmonic metrics. The underlying objects should be polystable.
- The “speed” of the rescaling action gives the slope/phase of the polystable object.
- For general objects, the flow should “decompose” the object into its polystable constituents, equipped with harmonic metrics.

The Harder-Narasimhan filtration only decomposes an object into *semistable* constituents.

Basic problem: Describe the decomposition (induced by the flow) of a semistable object into polystable pieces.

\mathcal{C} stable ∞ -category equipped with Bridgeland stability condition $\{\mathcal{C}_\theta^{ss}\}_{\theta \in \mathbb{R}}$, $Z : K_0(\mathcal{C}) \rightarrow \mathbb{C}$.

For each $\theta \in \mathbb{R}$, \mathcal{C}_θ^{ss} is an Artinian abelian category equipped with a homomorphism

$$X := \exp(-i\theta)Z : K_0(\mathcal{C}_\theta^{ss}) \rightarrow \mathbb{R}$$

which is positive on non-zero objects.

Natural filtrations

\mathcal{A} Artinian abelian category; $E \in \mathcal{E}$

$0 = E_0 \subset E_1 \subset E_2 \subset \dots \subset E_n = E$ filtration.

- ① Socle: E_k is maximal containing E_{k-1} such that E_k/E_{k-1} is semisimple (one extreme).

Natural filtrations

\mathcal{A} Artinian abelian category; $E \in \mathcal{E}$

$0 = E_0 \subset E_1 \subset E_2 \subset \dots \subset E_n = E$ filtration.

- 1 Socle: E_k is maximal containing E_{k-1} such that E_k/E_{k-1} is semisimple (one extreme).
- 2 Cosocle: E_k is minimal contained in E_{k+1} such that E_{k+1}/E_k is semisimple (another extreme).

Natural filtrations

\mathcal{A} Artinian abelian category; $E \in \mathcal{E}$

$0 = E_0 \subset E_1 \subset E_2 \subset \dots \subset E_n = E$ filtration.

- 1 Socle: E_k is maximal containing E_{k-1} such that E_k/E_{k-1} is semisimple (one extreme).
- 2 Cosocle: E_k is minimal contained in E_{k+1} such that E_{k+1}/E_k is semisimple (another extreme).
- 3 Let \mathcal{A} be the category of pairs (V, N) consisting of a vector space V and a nilpotent endomorphism N . Then there is a unique filtration labelled by half-integers such that

$$N^k : Gr_{k/2} V \rightarrow Gr_{-k/2} V$$

is an isomorphism for all k . (Balanced; this is the weight/Lefschetz filtration from mixed Hodge theory).

Balanced filtration

Theorem (Haiden-Katzarkov-Kontsevich-P.)

A Artinian abelian category, $X : K_0(\mathcal{A}) \rightarrow \mathbb{R}$, positive on non-zero objects, $E \in \mathcal{A}$. Then there exists a unique \mathbb{R} -filtration

$$0 = E_0 \subset E_1 \subset \dots \subset E_n = E$$

labelled by

$$\lambda_1 < \lambda_2 < \dots < \lambda_n$$

Balanced filtration

Theorem (Haiden-Katzarkov-Kontsevich-P.)

A Artinian abelian category, $X : K_0(\mathcal{A}) \rightarrow \mathbb{R}$, positive on non-zero objects, $E \in \mathcal{A}$. Then there exists a unique \mathbb{R} -filtration

$$0 = E_0 \subset E_1 \subset \dots \subset E_n = E$$

labelled by

$$\lambda_1 < \lambda_2 < \dots < \lambda_n$$

characterized by

- 1 *Paracomplementedness: E_j/E_{k-1} is semisimple whenever $\lambda_j - \lambda_k < 1$.*

Balanced filtration

Theorem (Haiden-Katzarkov-Kontsevich-P.)

A Artinian abelian category, $X : K_0(\mathcal{A}) \rightarrow \mathbb{R}$, positive on non-zero objects, $E \in \mathcal{A}$. Then there exists a unique \mathbb{R} -filtration

$$0 = E_0 \subset E_1 \subset \dots \subset E_n = E$$

labelled by

$$\lambda_1 < \lambda_2 < \dots < \lambda_n$$

characterized by

- 1 *Paracomplementedness: E_j/E_{k-1} is semisimple whenever $\lambda_j - \lambda_k < 1$.*
- 2 *Balancing condition: $\sum_j \lambda_j X(E_j/E_{j-1}) = 0$*

Balanced filtration

Theorem (Haiden-Katzarkov-Kontsevich-P.)

A Artinian abelian category, $X : K_0(\mathcal{A}) \rightarrow \mathbb{R}$, positive on non-zero objects, $E \in \mathcal{A}$. Then there exists a unique \mathbb{R} -filtration

$$0 = E_0 \subset E_1 \subset \dots \subset E_n = E$$

labelled by

$$\lambda_1 < \lambda_2 < \dots < \lambda_n$$

characterized by

- 1 *Paracomplementedness: E_j/E_{k-1} is semisimple whenever $\lambda_j - \lambda_k < 1$.*
- 2 *Balancing condition: $\sum_j \lambda_j X(E_j/E_{j-1}) = 0$*
- 3 *For any F_j with $E_{j-1} \subset F_j \subset E_j$ such that F_j/F_k is semisimple for $\lambda_j - \lambda_k \leq 1$, we have*

$$\sum_j \lambda_j X(F_j/E_{j-1}) \leq 0$$

Iterated balanced filtration and asymptotics

The last condition can be formulated as stability of the filtration $F^\lambda E$ considered as an object in an auxiliary abelian category \rightsquigarrow

Theorem (Haiden-Katzarkov-Kontsevich-P.)

- *Iterating the construction of the previous theorem gives a canonical filtration of E labelled by \mathbb{R}^∞ equipped with the lexicographic order.*

Iterated balanced filtration and asymptotics

The last condition can be formulated as stability of the filtration $F^\lambda E$ considered as an object in an auxiliary abelian category \rightsquigarrow

Theorem (Haiden-Katzarkov-Kontsevich-P.)

- *Iterating the construction of the previous theorem gives a canonical filtration of E labelled by \mathbb{R}^∞ equipped with the lexicographic order.*
- *When $\mathcal{A} = \text{Rep}(Q)$ this filtration controls the asymptotic behavior of the gradient flow on the space of metrics*

$$\log|h(t)| = \lambda_1 \log t + \lambda_2 \log \log t + \dots + \lambda_n \log^{(n)} t + O(1)$$

on the $(\lambda_1, \lambda_2, \dots, \lambda_n)$ piece of the filtration.

Iterated balanced filtration and asymptotics

The last condition can be formulated as stability of the filtration $F^\lambda E$ considered as an object in an auxiliary abelian category \rightsquigarrow

Theorem (Haiden-Katzarkov-Kontsevich-P.)

- Iterating the construction of the previous theorem gives a canonical filtration of E labelled by \mathbb{R}^∞ equipped with the lexicographic order.
- When $\mathcal{A} = \text{Rep}(Q)$ this filtration controls the asymptotic behavior of the gradient flow on the space of metrics

$$\log|h(t)| = \lambda_1 \log t + \lambda_2 \log \log t + \dots + \lambda_n \log^{(n)} t + O(1)$$

on the $(\lambda_1, \lambda_2, \dots, \lambda_n)$ piece of the filtration.

Meta-principle: The asymptotic dynamics of geometric flows (e.g., mean curvature flow, Yang-Mills flow) can be reduced to the finite dimensional quiver situation using the theory of **center manifolds**.

Dynamical systems from quiver representations

$Q = (Q_0, Q_1)$ quiver; Q_0 vertices, Q_1 arrows.

Quiver representation:

Vertex $i \mapsto E_i$ vector space.

Arrow $\alpha : i \rightarrow j \mapsto T_\alpha : E_i \rightarrow E_j$ operator.

Metrized quiver representation: hermitian metric h_i on E_i

\rightsquigarrow adjoint operator $T_\alpha^* : E_j \rightarrow E_i$.

Choosing “masses” $(m_i)_{i \in Q_0} \rightsquigarrow$ **flow on the space of metrics.**

$$m_i h_i^{-1} \dot{h}_i = \sum_{\alpha: i \rightarrow j} h_i^{-1} T_\alpha^* h_j T_\alpha - \sum_{\alpha: k \rightarrow i} T_\alpha h_j^{-1} T_\alpha^* h_i$$

This is asymptotic to the previous flow when the central charge takes values in a ray (the positive reals).

X compact Riemann surface, Kähler form ω , E finite dimensional holomorphic vector bundle on X , and h a hermitian metric on E . Consider the flow:

$$h^{-1}\partial_t h = -2i(\Lambda F - \lambda)$$

Theorem (Haiden-Katzarkov-Kontsevich-P.)

There is a canonical filtration $F^k E =: E_k$ on E labelled by

$$\beta_k \in \mathbb{R}t \oplus \mathbb{R} \log t \oplus \mathbb{R} \log \log t \oplus \dots \simeq \mathbb{R}^\infty$$

such that

$$\|\log h(t)|_{E_k}\| = \beta_k + O(1)$$

E_k/E_{k-1} is a sum of stable bundles of slope μ_k given by

$$\beta_k = 4\pi \left(\int_X \omega \right)^{-1} (\mu_k - \mu(E))t + \dots$$

Iterated Logarithms from a dynamical system

$$\log^{(1)}(t) := \log t$$

$$\log^{(n)}(t) := \log(\log^{(n-1)} t)$$

Iterated Logarithms from a dynamical system

$$\log^{(1)}(t) := \log t$$

$$\log^{(n)}(t) := \log(\log^{(n-1)} t)$$

$$\dot{x}_1 = e^{-x_1} \Rightarrow x_1 = \log t$$

Iterated Logarithms from a dynamical system

$$\log^{(1)}(t) := \log t$$

$$\log^{(n)}(t) := \log(\log^{(n-1)} t)$$

$$\dot{x}_1 = e^{-x_1} \Rightarrow x_1 = \log t$$

$$\dot{x}_2 = e^{-(x_1+x_2)} \Rightarrow \dot{x}_2 = \frac{1}{t} e^{-x_2}$$

Iterated Logarithms from a dynamical system

$$\log^{(1)}(t) := \log t$$

$$\log^{(n)}(t) := \log(\log^{(n-1)} t)$$

$$\dot{x}_1 = e^{-x_1} \Rightarrow x_1 = \log t$$

$$\dot{x}_2 = e^{-(x_1+x_2)} \Rightarrow \dot{x}_2 = \frac{1}{t} e^{-x_2} \Leftrightarrow \frac{d}{d \log t} x_2 = e^{-x_2}$$

Iterated Logarithms from a dynamical system

$$\log^{(1)}(t) := \log t$$

$$\log^{(n)}(t) := \log(\log^{(n-1)} t)$$

$$\dot{x}_1 = e^{-x_1} \Rightarrow x_1 = \log t$$

$$\dot{x}_2 = e^{-(x_1+x_2)} \Rightarrow \dot{x}_2 = \frac{1}{t} e^{-x_2} \Leftrightarrow \frac{d}{d \log t} x_2 = e^{-x_2} \Rightarrow x_2 = \log^{(2)} t$$

Iterated Logarithms from a dynamical system

$$\log^{(1)}(t) := \log t$$

$$\log^{(n)}(t) := \log(\log^{(n-1)} t)$$

$$\dot{x}_1 = e^{-x_1} \Rightarrow x_1 = \log t$$

$$\dot{x}_2 = e^{-(x_1+x_2)} \Rightarrow \dot{x}_2 = \frac{1}{t} e^{-x_2} \Leftrightarrow \frac{d}{d \log t} x_2 = e^{-x_2} \Rightarrow x_2 = \log^{(2)} t$$

$$\dot{x}_3 = e^{-(x_1+x_2+x_3)} \Leftrightarrow \frac{d}{d \log t} x_3 = e^{-(x_2+x_3)}$$

Iterated Logarithms from a dynamical system

$$\log^{(1)}(t) := \log t$$

$$\log^{(n)}(t) := \log(\log^{(n-1)} t)$$

$$\dot{x}_1 = e^{-x_1} \Rightarrow x_1 = \log t$$

$$\dot{x}_2 = e^{-(x_1+x_2)} \Rightarrow \dot{x}_2 = \frac{1}{t} e^{-x_2} \Leftrightarrow \frac{d}{d \log t} x_2 = e^{-x_2} \Rightarrow x_2 = \log^{(2)} t$$

$$\dot{x}_3 = e^{-(x_1+x_2+x_3)} \Leftrightarrow \frac{d}{d \log t} x_3 = e^{-(x_2+x_3)} \Rightarrow x_3 = \log^{(3)} t$$

⋮

$$\dot{x}_n = e^{-(x_1+x_2+\dots+x_n)}$$

Iterated Logarithms from a dynamical system

$$\log^{(1)}(t) := \log t$$

$$\log^{(n)}(t) := \log(\log^{(n-1)} t)$$

$$\dot{x}_1 = e^{-x_1} \Rightarrow x_1 = \log t$$

$$\dot{x}_2 = e^{-(x_1+x_2)} \Rightarrow \dot{x}_2 = \frac{1}{t} e^{-x_2} \Leftrightarrow \frac{d}{d \log t} x_2 = e^{-x_2} \Rightarrow x_2 = \log^{(2)} t$$

$$\dot{x}_3 = e^{-(x_1+x_2+x_3)} \Leftrightarrow \frac{d}{d \log t} x_3 = e^{-(x_2+x_3)} \Rightarrow x_3 = \log^{(3)} t$$

⋮

$$\dot{x}_n = e^{-(x_1+x_2+\dots+x_n)} \Leftrightarrow \frac{d}{d \log t} x_n = e^{-(x_2+\dots+x_n)}$$

Iterated Logarithms from a dynamical system

$$\log^{(1)}(t) := \log t$$

$$\log^{(n)}(t) := \log(\log^{(n-1)} t)$$

$$\dot{x}_1 = e^{-x_1} \Rightarrow x_1 = \log t$$

$$\dot{x}_2 = e^{-(x_1+x_2)} \Rightarrow \dot{x}_2 = \frac{1}{t} e^{-x_2} \Leftrightarrow \frac{d}{d \log t} x_2 = e^{-x_2} \Rightarrow x_2 = \log^{(2)} t$$

$$\dot{x}_3 = e^{-(x_1+x_2+x_3)} \Leftrightarrow \frac{d}{d \log t} x_3 = e^{-(x_2+x_3)} \Rightarrow x_3 = \log^{(3)} t$$

⋮

$$\dot{x}_n = e^{-(x_1+x_2+\dots+x_n)} \Leftrightarrow \frac{d}{d \log t} x_n = e^{-(x_2+\dots+x_n)} \Rightarrow x_n = \log^{(n)} t$$

The original **system of n differential equations** reduces to an identical **system of n-1 equations** in one less variable upon passing to **logarithmic time** $x_1 = s := \log t$.

1 dim representations

Input:

- 1 Directed acyclic graph $G = (G_0, G_1)$

1 dim representations

Input:

- 1 Directed acyclic graph $G = (G_0, G_1)$
- 2 Masses $(m_i)_{i \in G_0} \in \mathbb{R}_{>0}^{G_0}$

1 dim representations

Input:

- 1 Directed acyclic graph $G = (G_0, G_1)$
- 2 Masses $(m_i)_{i \in G_0} \in \mathbb{R}_{>0}^{G_0} \rightsquigarrow$ metric $\sum m_i(dx_i)^2$ on \mathbb{R}^{G_0} .

1 dim representations

Input:

- 1 Directed acyclic graph $G = (G_0, G_1)$
- 2 Masses $(m_i)_{i \in G_0} \in \mathbb{R}_{>0}^{G_0} \rightsquigarrow$ metric $\sum m_i (dx_i)^2$ on \mathbb{R}^{G_0} .
- 3 Weights $(c_\alpha)_{\alpha \in G_1} \in \mathbb{R}_{>0}^{G_1}$

1 dim representations

Input:

- 1 Directed acyclic graph $G = (G_0, G_1)$
- 2 Masses $(m_i)_{i \in G_0} \in \mathbb{R}_{>0}^{G_0} \rightsquigarrow$ metric $\sum m_i (dx_i)^2$ on \mathbb{R}^{G_0} .
- 3 Weights $(c_\alpha)_{\alpha \in G_1} \in \mathbb{R}_{>0}^{G_1} \rightsquigarrow$ action functional $S : \mathbb{R}^{G_0} \rightarrow \mathbb{R}$

$$S(x) := \sum_{\alpha: i \rightarrow j} c_\alpha e^{x_j - x_i}$$

1 dim representations

Input:

- 1 Directed acyclic graph $G = (G_0, G_1)$
- 2 Masses $(m_i)_{i \in G_0} \in \mathbb{R}_{>0}^{G_0} \rightsquigarrow$ metric $\sum m_i (dx_i)^2$ on \mathbb{R}^{G_0} .
- 3 Weights $(c_\alpha)_{\alpha \in G_1} \in \mathbb{R}_{>0}^{G_1} \rightsquigarrow$ action functional $S : \mathbb{R}^{G_0} \rightarrow \mathbb{R}$

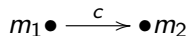
$$S(x) := \sum_{\alpha: i \rightarrow j} c_\alpha e^{x_j - x_i}$$

\rightsquigarrow gradient flow of S with respect to metric

$$m_i \dot{x}_i = \sum_{\alpha: i \rightarrow j} c_\alpha e^{x_j - x_i} - \sum_{\alpha: k \rightarrow i} c_\alpha e^{x_i - x_k}$$

Claim: The asymptotic behavior of these dynamical systems is controlled by iterated logarithms.

An example



Gradient flow:

$$m_1 \dot{x}_1 = ce^{x_2 - x_1}$$

$$m_2 \dot{x}_2 = -ce^{x_2 - x_1}$$

Solution:

$$x_1(t) = \frac{m_2}{m_1 + m_2} \log t + \log c_1$$

$$x_2(t) = -\frac{m_1}{m_1 + m_2} \log t + \log c_2$$

Where

$$\frac{c_2}{c_1} = \frac{m_1 m_2}{c(m_1 + m_2)}$$

General case

Ansatz: $x_i = v_i \log t + b_i$; $v_i, b_i \in \mathbb{R}$.

$$\rightsquigarrow \frac{m_j v_j}{t} = \sum_{\alpha: i \rightarrow j} c_\alpha t^{v_j - v_i} e^{b_j - b_i} - \sum_{\alpha: k \rightarrow i} c_\alpha t^{v_i - v_k} e^{b_i - b_k}$$

General case

Ansatz: $x_j = v_j \log t + b_j$; $v_j, b_j \in \mathbb{R}$.

$$\rightsquigarrow \frac{m_j v_j}{t} = \sum_{\alpha: i \rightarrow j} c_\alpha t^{v_j - v_i} e^{b_j - b_i} - \sum_{\alpha: k \rightarrow i} c_\alpha t^{v_i - v_k} e^{b_i - b_k}$$

Interested in asymptotic behavior of x_j upto $O(1)$, so look for solutions $x_j(t)$ of the differential equation correct upto terms in $L^1(\mathbb{R})$.

\implies only powers $t^{\leq -1}$ in RHS

General case

Ansatz: $x_i = v_i \log t + b_i$; $v_i, b_i \in \mathbb{R}$.

$$\rightsquigarrow \frac{m_i v_i}{t} = \sum_{\alpha: i \rightarrow j} c_\alpha t^{v_j - v_i} e^{b_j - b_i} - \sum_{\alpha: k \rightarrow i} c_\alpha t^{v_i - v_k} e^{b_i - b_k}$$

Interested in asymptotic behavior of x_i upto $O(1)$, so look for solutions $x_i(t)$ of the differential equation correct upto terms in $L^1(\mathbb{R})$.

\implies only powers $t^{\leq -1}$ in RHS

$\implies v_i - v_j \geq 1$ if $\exists \alpha : i \rightarrow j \Leftrightarrow (v_i)_i$ is an admissible grading (defn)

General case

Ansatz: $x_i = v_i \log t + b_i$; $v_i, b_i \in \mathbb{R}$.

$$\rightsquigarrow \frac{m_i v_i}{t} = \sum_{\alpha: i \rightarrow j} c_\alpha t^{v_j - v_i} e^{b_j - b_i} - \sum_{\alpha: k \rightarrow i} c_\alpha t^{v_i - v_k} e^{b_i - b_k}$$

Interested in asymptotic behavior of x_i upto $O(1)$, so look for solutions $x_i(t)$ of the differential equation correct upto terms in $L^1(\mathbb{R})$.

\implies only powers $t^{\leq -1}$ in RHS

$\implies v_i - v_j \geq 1$ if $\exists \alpha : i \rightarrow j \Leftrightarrow (v_i)_i$ is an admissible grading (defn)

comparing coefficients

$\implies m_i v_i = \sum_{\alpha: i \rightarrow j} c_\alpha u_\alpha - \sum_{\alpha: k \rightarrow i} c_\alpha u_\alpha$, and $u_\alpha = 0$ if $v_i - v_j > 1$.

Here $u_\alpha := e^{b_j - b_i} \in \mathbb{R}_{>0}$ for $\alpha : i \rightarrow j$.

General case

Ansatz: $x_i = v_i \log t + b_i$; $v_i, b_i \in \mathbb{R}$.

$$\rightsquigarrow \frac{m_i v_i}{t} = \sum_{\alpha: i \rightarrow j} c_\alpha t^{v_j - v_i} e^{b_j - b_i} - \sum_{\alpha: k \rightarrow i} c_\alpha t^{v_i - v_k} e^{b_i - b_k}$$

Interested in asymptotic behavior of x_i upto $O(1)$, so look for solutions $x_i(t)$ of the differential equation correct upto terms in $L^1(\mathbb{R})$.

\implies only powers $t^{\leq -1}$ in RHS

$\implies v_i - v_j \geq 1$ if $\exists \alpha : i \rightarrow j \Leftrightarrow (v_i)_i$ is an admissible grading (defn)

comparing coefficients

$\implies m_i v_i = \sum_{\alpha: i \rightarrow j} c_\alpha u_\alpha - \sum_{\alpha: k \rightarrow i} c_\alpha u_\alpha$, and $u_\alpha = 0$ if $v_i - v_j > 1$.

Here $u_\alpha := e^{b_j - b_i} \in \mathbb{R}_{>0}$ for $\alpha : i \rightarrow j$.

Key observation: u_α 's are Lagrange multipliers for a convex optimization problem.

Balanced weight grading

$C :=$ set of admissible gradings $\subset \mathbb{R}^{G_0}$ (convex body).

$M : C \rightarrow \mathbb{R}_{\geq 0}$; $M((v_i)_i) := \sum_i m_i v_i^2$ convex function.

Proposition

TFAE

- 1 $(v_i)_i$ minimizes M .
- 2 $\exists u_\alpha \geq 0 \alpha \in G_1$ satisfying

$$m_i v_i = \sum_{\alpha: i \rightarrow j} c_\alpha u_\alpha - \sum_{\alpha: k \rightarrow i} c_\alpha u_\alpha$$

Balanced weight grading

$C :=$ set of admissible gradings $\subset \mathbb{R}^{G_0}$ (convex body).
 $M : C \rightarrow \mathbb{R}_{\geq 0}$; $M((v_i)_i) := \sum_i m_i v_i^2$ convex function.

Proposition

TFAE

- 1 $(v_i)_i$ minimizes M .
- 2 $\exists u_\alpha \geq 0 \alpha \in G_1$ satisfying

$$m_i v_i = \sum_{\alpha: i \rightarrow j} c_\alpha u_\alpha - \sum_{\alpha: k \rightarrow i} c_\alpha u_\alpha$$

- 3 (i) $\sum_i m_i v_i = 0$

Balanced weight grading

$C :=$ set of admissible gradings $\subset \mathbb{R}^{G_0}$ (convex body).

$M : C \rightarrow \mathbb{R}_{\geq 0}$; $M((v_i)_i) := \sum_i m_i v_i^2$ convex function.

Proposition

TFAE

- 1 $(v_i)_i$ minimizes M .
- 2 $\exists u_\alpha \geq 0 \alpha \in G_1$ satisfying

$$m_i v_i = \sum_{\alpha: i \rightarrow j} c_\alpha u_\alpha - \sum_{\alpha: k \rightarrow i} c_\alpha u_\alpha$$

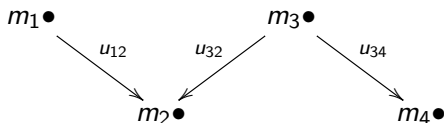
- 3 (i) $\sum_i m_i v_i = 0$ and (ii) $\sum_{i \in E} m_i v_i \leq 0$ for all $E \subset G_0$ such that $i \in G_0$ and $\exists \alpha : i \rightarrow j \implies j \in E$ “slope semistability”.

Unique grading satisfying (1)-(3) is called the **balanced weight grading**.

Iterated balanced weight grading

There are walls in the parameter space of m_i 's (recall: $(m_i)_i \in \mathbb{R}_{>0}^{G_0}$ parametrize certain metrics on \mathbb{R}^{G_0}) along which the **some of the $u_\alpha = 0$** for $\alpha : i \rightarrow j$ with $v_i - v_j = 1$.

Simplest example:



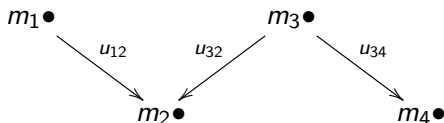
It turns out $u_{32} = \frac{m_2 m_3 - m_1 m_4}{\sum_i m_i}$.

Wall: $m_2 m_3 = m_1 m_4$.

Iterated balanced weight grading

There are walls in the parameter space of m_i 's (recall: $(m_i)_i \in \mathbb{R}_{>0}^{G_0}$ parametrize certain metrics on \mathbb{R}^{G_0}) along which the **some of the $u_\alpha = 0$** for $\alpha : i \rightarrow j$ with $v_i - v_j = 1$.

Simplest example:



It turns out $u_{32} = \frac{m_2 m_3 - m_1 m_4}{\sum_i m_i}$.

Wall: $m_2 m_3 = m_1 m_4$.

\rightsquigarrow Iterate procedure along a certain subgraph \rightsquigarrow **asymptotics governed by iterated logarithms along wall.**