

Twistor Spaces and Special Holonomy

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Plan

1. Twistor spaces of 4-manifolds

Some background, and their role in creating special geometries.

2. A circle action on the cone $\mathbb{R}^+ \times \mathbb{C}\mathbb{P}^3$ with G_2 holonomy

Illustrating its projection to a singular space $\mathbb{R}^6 = \mathbb{R}^3 \times \mathbb{R}^3$ à la Atiyah-Witten.

3. $SU(3)$ structure invariant by $SO(3)$

Diagnosing the geometry induced by G_2 on \mathbb{R}^6 in the same example.

Parts 2 and 3 represent joint work with Bobby Acharya and Robert Bryant, naïvely inspired by the successful use by Foscolo-Haskins-Nordström of circle bundles to construct new manifolds with G_2 holonomy.

1.1 Penrose's twistor theory

is based on choosing a real form of the Klein correspondence between lines in complex projective 3-space $\mathbb{C}\mathbb{P}^3$ and points in the quadric Q^4 :

$$\begin{array}{ccc}
 & \mathbb{F}_{1,2}(\mathbb{C}^4) & \\
 \swarrow & & \searrow \\
 \mathbb{C}\mathbb{P}^3 & & \text{Gr}_2(\mathbb{C}^4) = Q^4 \subset \mathbb{C}\mathbb{P}^5
 \end{array}
 \quad \begin{array}{l}
 \pi \in \Lambda^2 \mathbb{C}^4 \\
 \pi \wedge \pi = 0
 \end{array}$$

The real form can be defined by a reduction

$$\text{SL}(4, \mathbb{C}) \supset \begin{cases} \text{SU}(2, 2) \simeq \text{SO}(4, 2) & \text{acting on } \mathcal{S}^3 \times \mathcal{S}^1 \supset \mathbb{R}^{3,1} \\ \text{SL}(2, \mathbb{H}) \simeq \text{SO}(5, 1) & \text{" } \mathbb{H}\mathbb{P}^1 = \mathcal{S}^4 \supset \mathbb{R}^4 \\ \text{SL}(4, \mathbb{R}) \simeq \text{SO}(3, 3) & \text{" } \text{Gr}_2(\mathbb{R}^4) \supset \mathbb{R}^{2,2}. \end{cases}$$

In the first case, a point $p \in \mathbb{R}^{3,1}$ defines a line in a real hypersurface \mathcal{PN} of $\mathbb{C}\mathbb{P}^3$. Two such $\mathbb{C}\mathbb{P}^1$'s intersect in $x \in \mathcal{PN}$ iff the points in $\mathbb{R}^{3,1}$ lie on a light ray, while a point $y \in \mathbb{C}\mathbb{P}^3 \setminus \mathcal{PN}$ defines a 3-parameter family of light rays in $\mathbb{R}^{3,1}$.

1.2 Hopf geometry

We shall concentrate on the second case in which the fibres of

$$\begin{array}{c} \mathbb{C}\mathbb{P}^3 \\ \pi \downarrow \\ \mathbb{H}\mathbb{P}^1 = \mathbb{S}^4 \subset \text{Gr}_2(\mathbb{C}^4) \end{array}$$

parametrize ‘real’ lines relative to the antilinear involution $j: \mathbb{C}\mathbb{P}^3 \rightarrow \mathbb{C}\mathbb{P}^3$, which acts as the antipodal map on each fibre $\mathbb{S}^2 \cong \mathbb{C}\mathbb{P}^1$. The fibres are complex, but they have non-trivial normal bundle $\mathcal{O}(1) \oplus \mathcal{O}(1)$.

Any point of $z \in \mathbb{C}\mathbb{P}^3$ will induce an almost complex structure on $T_{\pi(z)}\mathbb{S}^4$, and a complex surface will define an integrable orthogonal complex structure (OCS) on an open subset of \mathbb{S}^4 .

Example. A plane $\mathbb{C}\mathbb{P}^2$ determines a (conformally) constant OCS on $\mathbb{R}^4 = \mathbb{S}^4 \setminus \infty$.

1.3 Associated bundles

In place of S^4 , start with any oriented Riemannian 4-manifold M . Its $SO(4)$ holonomy defines a splitting

$$\Lambda^2 T^*M = \Lambda^+ \oplus \Lambda^-$$

$$\begin{array}{c} Z \subset \Lambda^- \\ \pi \downarrow \\ M. \end{array}$$

and one can construct the 2-sphere bundle

Each point $z \in \pi^{-1}(m)$ defines an almost complex structure on its horizontal space $H_z \cong T_m M$ (relative to the LeviCivita connection), which can be combined with (1) the natural complex structure on $V_z \cong T_z S^2$, or (2) its negative. This equips Z with almost complex structures J_1, J_2 ; the latter is never integrable but $c_1(J_2) = 0$.

The $SO(4)$ -structure on the 7-dimensional total space Λ^- is compatible with the representation $SO(4) \subset G_2 \subset SO(7)$.

1.4 Self-duality in 4 dimensions

A local section $s: U \rightarrow Z$ determines an almost Hermitian structure (g, J_s, ω_s) on M . The map s is

- J_1 -holomorphic iff J_s is integrable
- J_2 -holomorphic iff $(d\omega_s)^{1,2} = 0$
- horizontal iff J_s is Kähler.

$$\begin{array}{ccc} & Z \subset \Lambda^- & \\ & \pi \downarrow & \\ U \subseteq M & & . \end{array}$$

Theorems.

J_1 is integrable iff M is self-dual, i.e. its Weyl tensor satisfies $W_- \equiv 0$ [Atiyah-Hitchin-Singer].

If (Z, J_1) is (compact) Kähler then M is isometric to S^4 or $\mathbb{C}P^2$ [Besse, Hitchin]. In the latter case $Z \cong SU(3)/T^2$.

Given M^4 (compact, oriented) there exists n such that $M \# n\mathbb{C}P^2$ admits a self-dual metric [Poon, LeBrun, Joyce; Floer, Donaldson-Friedman, Taubes].

1.5 Twistor lifts

Let Σ be a Riemann surface. An immersion

$$\phi: \Sigma \longrightarrow M$$

can be lifted to $\psi: \Sigma \rightarrow Z$, so as to render $\phi_*(T_\sigma\Sigma)$ complex.

Proposition [Eells-S, Lichnerowicz]. ϕ is harmonic iff ψ is J_2 -holomorphic.

Examples. If ψ is also J_1 -holomorphic then ϕ is ‘superminimal’. Such immersions can be constructed for any genus using Bryant’s formula $\left[1, f - \frac{1}{2}g \frac{df}{dg}, g, \frac{1}{2} \frac{df}{dg}\right]$.

In the case $M = S^4$ or $\mathbb{C}\mathbb{P}^2$, the twistor space (Z, J_2) admits a compatible ‘nearly Kähler’ (non-standard Einstein) metric h . It follows that the cone $\mathbb{R}^+ \times Z$ admits a Ricci-flat metric $dr^2 + r^2h$ with holonomy G_2 [Bär].

1.6 Symplectic Calabi-Yau spaces

can be constructed from twistor spaces [Fine-Panov].

Take M to be real hyperbolic 4-space. Then Z admits a symplectic form taming J_2 and $c_1(J_2) = 0$.

Z is symplectomorphic to $\mathcal{O}(-1) \oplus \mathcal{O}(-1) \rightarrow \mathbb{C}\mathbb{P}^1$, a small resolution of the conifold $\{wx - yz = 0\}$ in \mathbb{C}^4 .

$$\begin{array}{c} Z \cong \frac{\mathrm{SO}(4, 1)}{\mathrm{U}(2)} \\ \pi \downarrow \\ \mathcal{H}^4. \end{array}$$

This construction can be applied to hyperbolic orbifolds \mathcal{H}^4/Γ by resolving the twistor space to obtain simply-connected examples with $b_3 = 0$ (so non-Kähler) and arbitrary b_2 . Higher dimensional twistor spaces (of even-dimensional Riemannian manifolds) provide further results.

1.7 G_2 holonomy

Theorem [Bryant-S]. If M is S^4 or $\mathbb{C}\mathbb{P}^2$ then the 7-manifold Λ^- admits a complete metric g with holonomy equal to G_2 and asymptotic to the cone over Z .

If r denotes norm in the fibres of Λ^- , one can express

$$g = (r^2 + 1)^{-1/2} g_{\text{ver}} + (r^2 + 1)^{1/2} g_{\text{hor}}.$$

Over S^4 , the associated 3-form φ on $\mathbb{R}^+ \times \mathbb{C}\mathbb{P}^3$ can be pulled back to \mathbb{C}^4 . Then $r = R^2$ where $R = \sum_{i=0}^3 |z_i|^2$ is the Euclidean norm squared, and

$$\varphi = d((R^4 + 1)^{1/4} \tau), \quad \tau = -dR \wedge \alpha_1 + \alpha_2 \wedge \alpha_3.$$

Together with a G_2 metric over S^3 , these were the only such AC metrics known until Foscolo-Haskins-Nordström established the existence of complete G_2 metrics on circle bundles $M_{m,n} \rightarrow K_{\mathbb{C}\mathbb{P}^1 \times \mathbb{C}\mathbb{P}^1}$ invariant by $SU(2)^2 \times U(1)$. These include ones that are asymptotic to cones over finite quotients of $S^3 \times S^3$.

2.1 M-theory

Regard $\mathbb{C}P^3$ as the quotient of S^7 inside $\mathbb{C}^4 = \mathbb{H}^2$ by $U(1)_R$, and $S^4 = S^7/Sp(1)_R$. We shall focus on $\mathcal{C}^7 = \mathbb{R}^+ \times \mathbb{C}P^3$, its conical metric with G_2 holonomy, and the quotient

$$\frac{\mathcal{C}^7}{U(1)_L} \stackrel{*}{=} \frac{\mathbb{C}^4}{T^2} \cong \frac{\mathbb{C}^2}{U(1)} \times \frac{\mathbb{C}^2}{U(1)} \cong \mathbb{R}^3 \times \mathbb{R}^3.$$

We use hyperkähler moment maps to describe the resulting projection

$$\mathcal{C}^7 \ni [z_0, z_1, z_2, z_3] \longmapsto (\mathbf{u}, \mathbf{v}) \in \mathbb{R}^6,$$

whose circle fibres collapse over $\mathbb{R}^3 \cup \mathbb{R}^3$. The G_2 metric on the cone relates to Type IIA string theory of \mathbb{R}^6 with a singular locus $\mathbb{R}^3 \cup \mathbb{R}^3$ as described by Atiyah-Witten, who state:

“details of the induced metric are unimportant”.

Nonetheless, we [Acharya-Bryant-S] set out describe the $SU(3)$ structure induced on \mathbb{R}^6 , using the bivector formalism.

2.2 Gibbons-Hawking coordinates

The action of $U(1)_L$ on \mathbb{C}^4 covers a rotation in 2 coordinates of S^4 :

$$\begin{array}{ccccccc} U(1)_L & \subset & U(2)_L & \subset & Sp(2)_L & & \\ & & & & \downarrow & & \\ SO(2) & \subset & SO(3) \times SO(2) & \subset & SO(5). & & \end{array}$$

To make $\mu: \mathcal{C}^7 \rightarrow \mathbb{R}^6$ explicit, observe that

$$\begin{array}{llll} U(1)_L & \text{acts on} & \mathbb{C}_{0123}^4 & \text{with weights } (1, 1, 1, 1) \\ U(1)_R & \text{"} & \text{"} & \text{" } (1, -1, 1, -1) \\ \implies T^2 & \text{acts on} & \mathbb{C}_{02}^2 \times \mathbb{C}_{13}^2 & \text{with weights } (1, 1) \times (1, 1). \end{array}$$

Then $\mathbf{u} = (u_1, u_2, u_3)$ and $\mathbf{v} = (v_1, v_2, v_3)$, where

$$u_1 = |z_0|^2 - |z_2|^2, \quad u_2 - iu_3 = z_0 \bar{z}_2; \quad v_1 = |z_1|^2 - |z_3|^2, \quad v_2 - iv_3 = z_1 \bar{z}_3.$$

Moreover $R = \sum_{i=0}^3 |z_i|^2$ equals $u + v$, where $u = |\mathbf{u}|$ and $v = |\mathbf{v}|$.

2.3 Eguchi-Hanson sheets

Provided $\mathbf{m} \in \mathbb{R}^3$ is non-zero, the hyperkähler quotient

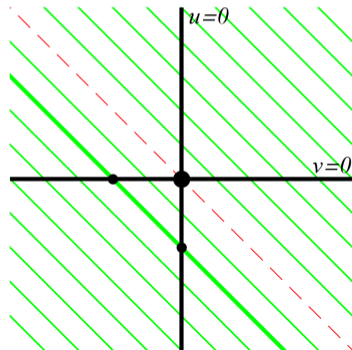
$$\frac{\{\mathbf{z} \in \mathbb{C}^4 : \mathbf{u} - \mathbf{v} = \mathbf{m}\}}{U(1)_R} \subset \mathcal{C}^7$$

can be identified with T^*S^2 endowed with a metric k of holonomy $SU(2)$. It has a triholomorphic action by $U(1)_L$ with moment map \mathbf{u} .

Its image in \mathbb{R}^6 acquires the harmonic function

$$V = \frac{1}{|\mathbf{u}|} + \frac{1}{|\mathbf{u} - \mathbf{m}|},$$

used to recover $k = V^{-1}\theta^2 + Vg_{\text{euc}}$. Each diagonal represents $\{(\mathbf{u}, \mathbf{v}) \in \mathbb{R}^6 : \mathbf{u} - \mathbf{v} = \mathbf{m}\}$.



2.4 Rotation of the 4-sphere

Consider again the reduction to $SO(3) \times SO(2)$:

$$\begin{array}{c} \mathcal{E}^7 = \mathbb{R}^+ \times \mathbb{C}\mathbb{P}^3 \\ \pi \downarrow \\ \mathbb{S}^4 \subset \mathbb{R}^2 \oplus \mathbb{R}^3 \end{array}$$

Let

- $\mathbb{S}^1 = \mathbb{S}^4 \cap \mathbb{R}^2$ be the fixed point set for the action of $SO(3)$
- $\mathbb{S}^2 = \mathbb{S}^4 \cap \mathbb{R}^3$ be the fixed point set for the action of $SO(2)$.

View $\mathbb{S}^4 \setminus \mathbb{S}^1$ as a trivial disk bundle over \mathbb{S}^2 , whose boundaries are fused into \mathbb{S}^1 . If X is the Killing field generated by $SO(2)$, then

$$X^\flat = (1 - s^2)dt,$$

where $t: \mathbb{S}^4 \setminus \mathbb{S}^1 \rightarrow [0, 2\pi)$ is 'longitude' and $s: \mathbb{S}^4 \rightarrow [0, 1]$ is sine of 'latitude'. In fact, s represents the radius in \mathbb{R}^3 under the projection $\mathbb{S}^4 \subset \mathbb{R}^5 \rightarrow \mathbb{R}^3$:

2.5 Reduced twistor fibration

Orthogonal projection $\mathbb{R}^5 \rightarrow \mathbb{R}^3$ identifies $S^4/\text{SO}(2)$ with the closed unit ball \bar{D}^3 whose boundary is effectively S^2 .

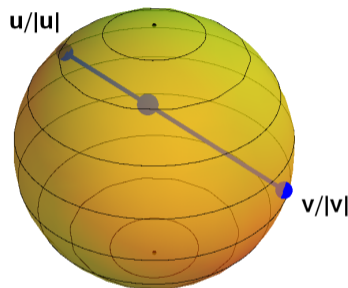
Proposition. The projection $\mathcal{C}^7/\text{U}(1)_L \rightarrow \bar{D}^3$ is given by

$$(\mathbf{u}, \mathbf{v}) \mapsto \frac{\mathbf{u} + \mathbf{v}}{u + v} = \frac{1}{R}(\mathbf{u} + \mathbf{v}),$$

and $s = |\mathbf{u} + \mathbf{v}|/R$ equals the radius in \bar{D}^3 .

Examples.

- (\mathbf{u}, \mathbf{v}) arises from a point of S^1 iff $\mathbf{u} + \mathbf{v} = \mathbf{0}$ (implying $u = v$).
- (\mathbf{u}, \mathbf{v}) maps into S^2 (equivalently $s = 1$) iff \mathbf{u} and \mathbf{v} are aligned.



2.6 Two quadrics

help to interpret the preceding geometry. Set

$$\begin{aligned}Q_+ &= \{[z_0, z_1, z_2, z_3] \in \mathbb{C}\mathbb{P}^3 : z_0\bar{z}_3 - \bar{z}_1z_2 = 0\} \\Q_- &= \{[z_0, z_1, z_2, z_3] \in \mathbb{C}\mathbb{P}^3 : z_0z_1 + z_2z_3 = 0\}.\end{aligned}$$

These subvarieties are both $SU(2)$ invariant, and arise from points of \mathbb{R}^6 where \mathbf{u}, \mathbf{v} are aligned (respectively, anti-aligned):

$$\mu(\mathbb{R}^+ \times Q_{\pm}) = \{(\mathbf{u}, \mathbf{v}) : \mathbf{u} \cdot \mathbf{v} = \pm uv\}.$$

While $\pi(Q_+) = S^2$ (making it obvious that $Q_+ \approx S^2 \times S^2$), the holomorphic one Q_- double covers

$$S^4 \setminus S^1 \cong \mathbb{R}^4 \setminus \mathbb{R} \cong S^2 \times \mathcal{H}^2,$$

encoding the scalar flat Kähler metric [Pontecorvo, S-Viaclovsky]. It is the locus of points in $\mathbb{C}\mathbb{P}^3$ for which the $U(1)_L$ orbits are horizontal over S^4 .

2.7 Coassociative subvarieties

The defining function for Q_+ equals

$$z_0 \bar{z}_3 - \bar{z}_1 z_2 = a e^{it},$$

where $a = 2\sqrt{uv - \mathbf{u} \cdot \mathbf{v}}$ so that $(a/R)^2 = 1 - s^2$. Both a and t are invariants for the action of $SO(3)$, as are u and v because $SO(3)$ acts diagonally on $(\mathbf{u}, \mathbf{v}) \in \mathbb{R}^6$.

By general principles, any 3-dimensional $SO(3)$ orbit is contained in a unique coassociative subvariety V of the G_2 manifold \mathcal{C}^7 (so $\varphi|_V \equiv 0$). For the chosen $SO(3)$, the resulting family has been described by Karigiannis-Lotay. Our task was to interpret this using \mathbf{u} and \mathbf{v} .

An $SO(3)$ orbit will intersect a twistor fibre S^2 of fixed radius over $p \in S^4 \setminus S^1$ in a parallel circle at 'height' $h \in [-1, 1]$ relative to the poles defined by Q_- . Define another $SO(3)$ invariant

$$b = u^2 - v^2 = R(u - v) = shR^2.$$

2.8 Coassociatives (continued)

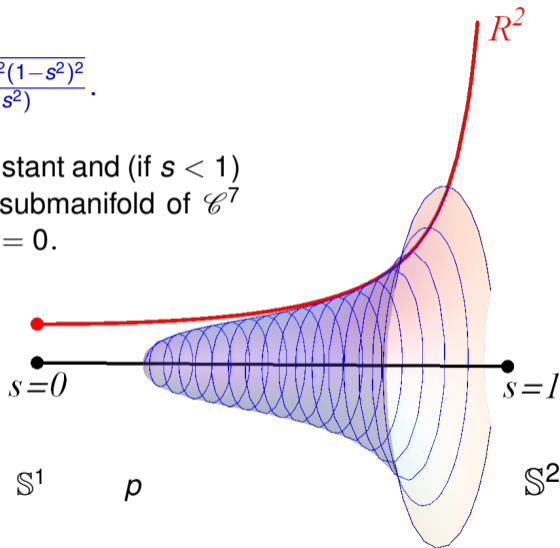
Sphere radius, $R^2 = \frac{a^2}{1-s^2}$

Circle radius, $R^2 \sqrt{1-h^2} = \frac{\sqrt{a^4 s^2 - b^2(1-s^2)^2}}{s(1-s^2)}$.

Theorem [KL, ABS]. Setting a, b constant and (if $s < 1$) t constant defines a coassociative submanifold of \mathcal{C}^7 diffeomorphic to T^*S^2 unless $a = b = 0$.

A fibre over $p \in S^2$ is shown for $(a, b, t) = (\frac{1}{2}, \frac{1}{4}, 0)$:

$a = 0$ gives coassociatives over S^2 , while $b = 0$ ($a \neq 0$) gives equators all the way to the twistor fibres over S^1 .



3.1 The induced metric

Let h be the conical metric on \mathcal{C}^7 with holonomy G_2 . We seek the metric g induced on $\mathbb{R}^6 \setminus (\mathbb{R}^3 \cup \mathbb{R}^3)$ by setting

$$h = \mu^*g + N\Theta^2,$$

where $\Theta = (X \lrcorner h)/N$ is the connection 1-form, and $N = h(X, X) = 6uv - 2\mathbf{u} \cdot \mathbf{v}$ measures the size of the circle fibres. This makes μ a Riemannian submersion.

Theorem [ABS].

$$g = \frac{1}{2}dR^2 + \frac{1}{2}|d\mathbf{u} + d\mathbf{v}|^2 + \frac{2}{N}|u d\mathbf{v} - v d\mathbf{u}|^2 + \frac{1}{2N}\Gamma_+^2 - \frac{1}{4N}\Gamma_-^2,$$

where

$$\Gamma_+ = u d\mathbf{v} + v d\mathbf{u} - \mathbf{u} \cdot d\mathbf{v} - \mathbf{v} \cdot d\mathbf{u},$$

$$\Gamma_- = u d\mathbf{v} - v d\mathbf{u} + \mathbf{u} \cdot d\mathbf{v} - \mathbf{v} \cdot d\mathbf{u}.$$

Example. If $u\mathbf{v} = \pm v\mathbf{u}$ then $\Gamma_{\pm} = 0$ (and $N = 4uv$ or $8uv$).

3.2 Two-dimensional quadrants

The formula for g simplifies on certain subvarieties of \mathbb{R}^6 . Consider the negative quadrant

$$\mathcal{L}^2 = \{(\mathbf{u}, \mathbf{v}) = (0, 0, u; 0, 0, -v), u, v > 0\} \subset \mathbb{R}^2.$$

Corollary. The restriction of g to \mathcal{L}^2 equals

$$\left(1 + \frac{v}{2u}\right) du^2 + du dv + \left(1 + \frac{u}{2v}\right) dv^2$$

and is locally Euclidean, i.e. $K \equiv 0$.

\mathcal{L}^2 is in fact superminimal, being the projection of (a cone over an open subset of) a horizontal projective line $\mathbb{C}P^1$ inside $Q_- \subset \mathbb{C}P^3$. We shall see that it is also \mathbb{J} -holomorphic, where \mathbb{J} is the induced almost complex structure on \mathbb{R}^6 .

3.3 Three-dimensional slices

Extend \mathcal{L}^2 to

$$\mathcal{L}^3 = \{(0, u \sin \theta, u \cos \theta; 0, -v \sin \theta, v \cos \theta)\}.$$

so that $\mathbf{u} \cdot \mathbf{v} = uv \cos 2\theta$, and set

$$u = R \cos^2\left(\frac{1}{2}\phi\right), \quad v = R \cos^2\left(\frac{1}{2}\phi\right)$$

so that $u + v = R$ and $b = R^2 \cos \phi$. The orbits of $\text{SO}(3)$ on \mathbb{R}^6 are parametrized by u, v, θ , so \mathcal{L}^3 is a slice to the orbits (expressed symmetrically in \mathbf{u}, \mathbf{v}).

Corollary. The restriction of g to \mathcal{L}^3 equals

$$dR^2 + \frac{1}{2}R^2[d\theta^2 + \frac{1}{4}(3 - \cos 2\theta)d\phi^2].$$

This is isometric to a cone over a surface of revolution, illustrated next.

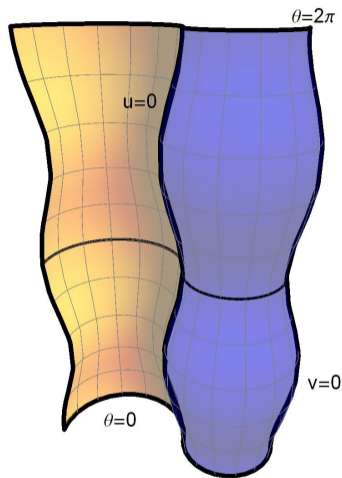
3.4 Slices (continued)

$$\text{Let } P = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix} \in \text{SO}(3).$$

Then \mathcal{L}^3 is the cone over the blue surface, and $P \cdot \mathcal{L}^3$ the cone over the yellow surface. Together these patches close up topologically to define a torus \mathcal{T} and $\mu^{-1}(\mathcal{T})$ is a cone over $S^1 \times S^2$.

Relative to the metric g , vectors in the respective the singular \mathbb{R}^3 axes meet at an angle of

$$\frac{1}{2}\pi \leq \pi \sqrt{\frac{3}{8} - \frac{1}{8} \cos \theta} \leq \frac{1}{\sqrt{2}}\pi.$$



3.5 The symplectic form

Recall that $\mu: \mathcal{C}^7 = \mathbb{R}^+ \times \mathbb{C}\mathbb{P}^3 \rightarrow \mathbb{R}^6$, and that $R = u + v = |\mathbf{u}| + |\mathbf{v}|$. An almost Kähler structure on \mathbb{R}^6 is defined by scaling g so that the symplectic form

$$\sigma = X \lrcorner \varphi$$

has constant norm. Here X is the Killing field generating $U(1)_L$.

Theorem. The vectors $\mathbf{p} = \mathbf{u} + \mathbf{v}$ and $\mathbf{q} = R(\mathbf{u} - \mathbf{v})$ furnish Darboux coordinates:

$$\sigma = -\frac{1}{2} \sum_{i=1}^3 dp_i \wedge dq_i.$$

Note that σ extends to $\mathbb{R}^3 \cup \mathbb{R}^3$ and is non-degenerate on $\mathbb{R}^6 \setminus \mathbf{0}$. The projections $(\mathbf{u}, \mathbf{v}) \mapsto R^{1/2}\mathbf{u}$ and $(\mathbf{u}, \mathbf{v}) \mapsto R^{1/2}\mathbf{v}$ also have Lagrangian fibres.

3.6 The SU(3) structure

This is determined by g and the $SL(3, \mathbb{C})$ structure encoded in a complex volume form Ψ . From the theory of stable forms, Ψ is determined by the closed 3-form

$$\operatorname{Re} \Psi = X \lrcorner (*\varphi),$$

which will involve the function $N = h(X, X) = 6uv - 2\mathbf{u} \cdot \mathbf{v}$.

Proposition.

$$\begin{aligned} 8uv \operatorname{Re} \Psi &= \frac{1}{6} v(N + 4v^2) \{d\mathbf{u}, d\mathbf{u}, d\mathbf{u}\} \\ &\quad - v(4u^2 + 3uv + \mathbf{u} \cdot \mathbf{v}) \{d\mathbf{v}, d\mathbf{u}, d\mathbf{u}\} \\ &\quad + ((u + 2v)\mathbf{v} \cdot d\mathbf{v} + v\mathbf{u} \cdot d\mathbf{v}) \wedge \{\mathbf{u}, d\mathbf{u}, d\mathbf{u}\} \\ &\quad + (v\mathbf{u} \cdot d\mathbf{v} - uv \cdot d\mathbf{v}) \wedge \{\mathbf{v}, d\mathbf{u}, d\mathbf{u}\} \\ &\quad + \text{terms interchanging } \mathbf{u} \text{ and } \mathbf{v} \end{aligned}$$

This is the closest we can get to an explicit description of the (non-integrable) almost complex structure \mathbb{J} on \mathbb{R}^6 , as there are no easy expressions for $(1, 0)$ forms.

3.7 Pseudo holomorphic surfaces

Proposition. The linear subvariety

$$\mathcal{L}^4 = \{(0, u_2, u_3; 0, v_2, v_3), uv \neq 0\}$$

is \mathbb{J} -holomorphic for the induced $SU(3)$ structure on \mathbb{R}^6 .

Applying $SO(3)$, there will be a family of such subvarieties (parametrized by \mathbb{RP}^2) that exhaust \mathbb{R}^6 . Any two intersect in a \mathbb{J} -holomorphic curve, isomorphic to \mathcal{L}^2 .

Unlike the case of standard $\mathbb{C}^3 = \mathbb{R}^3 \oplus \mathbb{J}\mathbb{R}^3$, we cannot extend this \mathbb{RP}^2 to $\text{Gr}_2(\mathbb{C}^3)$.

The action of $SO(3)$ on \mathbb{C}^3 has been used to construct invariant Kähler-Einstein metrics on \mathbb{CP}^2 minus the conic curve $u = v$ with cone angle lying in $(\frac{1}{2}\pi, 2\pi]$ [C. Li, Dancer-Strachan] and associated Calabi-Yau cones.

3.8 Conclusion

We have analysed a quotient of nearly Kähler $\mathbb{C}\mathbb{P}^3$ and its G_2 cone by $U(1)$. It is convenient to work on \mathbb{C}^4 and (via the Gibbons-Hawking ansatz) identify the quotient with $\mathbb{C}^4/T^2 \cong \mathbb{R}^6$. In the holomorphic setting, all the formulae are simpler and related to the Kähler quotient

$$\mathbb{C}\mathbb{P}^3//U(1) \cong \mathbb{C}\mathbb{P}^1 \times \mathbb{C}\mathbb{P}^1.$$

For G_2 , we can easily describe the symplectic form and also the curvature 2-form $F = d\Theta$ of μ , but pinning \mathbb{J} down is more difficult. Some modification is necessary when starting with the complete G_2 metric on $\Lambda^-T^*S^4$.

There remains the motivating conjecture that $\mathbb{R}^+ \times \mathbb{W}\mathbb{C}\mathbb{P}_{p,p,q,q}^3$ carries a metric with holonomy G_2 [Acharya-Witten]. The constructions can be generalized to a circle acting with different weights on \mathbb{C}^4 , or actions on other G_2 manifolds, though this study will involve real invariant theory outside the familiar hyperkähler setting.