

Algebraically Constrained Special Holonomy Metrics and Second-order Associative 3-folds

A progress report

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Part I: Curvature-Constrained Special Holonomy

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$$d\eta = -\theta \wedge \eta \quad \text{and} \quad d\theta = -\theta \wedge \theta + R(\eta \wedge \eta).$$

$\eta : TB \rightarrow \mathbb{R}^n$, $\theta : TB \rightarrow \mathfrak{h}$, and $R : B \rightarrow K(\mathfrak{h})$ is the **curvature function**, where $K(\mathfrak{h})$ is the H -representation

$$0 \longrightarrow K(\mathfrak{h}) \longrightarrow S^2(\mathfrak{h}) \xrightarrow{\wedge} \Lambda^4(\mathbb{R}^n).$$

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Second Bianchi: $dR = -\theta.R + R'(\eta)$. where

$$R' : B \rightarrow K^{(1)}(\mathfrak{h}) \subset \text{Hom}(\mathbb{R}^n, K(\mathfrak{h}))$$

represents the covariant derivative of the curvature.

Example: $SU(2) \subset SO(4)$

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$$K(\mathfrak{su}(2)) = S_0^2(\mathbb{R}^3) \simeq \mathbb{R}^5 \quad \text{and} \quad K^{(1)}(\mathfrak{su}(2)) \simeq \mathbb{C}^6 \simeq S^5(\mathbb{C}^2)$$

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É. Cartan (1926): $SU(2)$ -holonomy depends on 2 functions of 3 variables.

Basic holonomy problem: For a given subgroup $H \subset SO(n)$ how to classify, up to local diffeomorphism, the 'solutions' to the structure equations

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Example: $H = SU(2) = \text{Spin}(3) \subset SO(4)$ acts on $K(\mathfrak{su}(2)) = S_0^2(\mathbb{R}^3)$ preserving the symmetric functions of the eigenvalues of $R \in S_0^2(\mathbb{R}^3)$. Specifying a relation between $\sigma_2(R)$ and $\sigma_3(R)$ defines such an invariant subset $A \subset S_0^2(\mathbb{R}^3)$.

$$\sigma_3(R)^2 + \frac{4}{27}\sigma_2(R)^3 \leq 0.$$

Cases of interest in special holonomy

1. $SU(n) \subset SO(2n)$

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2. $G_2 \subset SO(7)$

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3. $\text{Spin}(7) \subset SO(8)$

$$K(\mathfrak{so}(7)) \simeq V^{0,2,0}(\mathfrak{so}(7)) \simeq \mathbb{R}^{168}.$$

Example: The structure equations for SU(2)-holonomy

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where $R_{ij} = R_{ji}$ with $R_{11} + R_{22} + R_{33} = 0$.

We have $A \simeq K(\mathfrak{su}(2)) \simeq \mathbb{R}^5$ with

$$(s_1, s_2, s_3, s_4, s_5, s_6, s_7) = (0, 3, 2, 0, 0, 0, 0).$$

and $\dim A^{(1)} = \dim K(\mathfrak{su}(2))^{(1)} = 12 = 2s_2 + 3s_3$, so it's involutive.

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Example: The $SU(2)$ structure equations in which $R : B \rightarrow S_0^2(\mathbb{R}^3)$ has a double eigenvalue everywhere are not involutive:

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Applying $d^2 = 0$ to the equations

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with $r \neq 0$ implies that there exist u_0, u_1, u_2, u_3 for which

$$dr = 4r (u_0 \eta_0 + u_1 \eta_1 + u_2 \eta_2 + u_3 \eta_3)$$

$$\theta_2 = 2 (-u_2 \eta_0 - u_3 \eta_1 + u_0 \eta_2 + u_1 \eta_3)$$

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These are structure equations for a coframing $(\eta_0, \eta_1, \eta_2, \eta_3, \theta_1)$ with coefficients (r, u_0, u_1, u_2, u_3) that still are not involutive.

Differentiating the structure equations again yields relations of the form

$$d \begin{pmatrix} u_0 \\ u_1 \\ u_2 \\ u_3 \end{pmatrix} = U(r, u_0, u_1, u_2, u_3, v_1, v_2, v_3) \begin{pmatrix} \theta_1 \\ \eta_0 \\ \eta_1 \\ \eta_2 \\ \eta_3 \end{pmatrix}$$

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Differentiating these last relations yields no more relations. Coupled with

$$dr = 4r(u_0 \eta_0 + u_1 \eta_1 + u_2 \eta_2 + u_3 \eta_3)$$

This gives 8 'independent' coefficients in the structure equations for which $d^2 = 0$ is an identity.

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3. $H = \mathrm{Spin}(7) \subset \mathrm{SO}(8)$: $s_7 = 12$ is last nonzero character.

Curvature restrictions in the $SU(2) \subset SO(4)$ case

The $SU(2)$ -invariants on $K(\mathfrak{su}(2)) \simeq S_0^2(\mathbb{R}^3) \simeq \mathbb{R}^5$ are generated by $\sigma_2, \sigma_3 : S_0^2(\mathbb{R}^3) \rightarrow \mathbb{R}$, satisfying

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3. $(\sigma_3(R))^2 + \frac{4}{27} (\sigma_2(R))^3 = 0$.

This is the 'double eigenvalue case', with nontrivial stabilizer $S^1 \subset SU(2)$.

Not involutive, but prolongation yields a 2-parameter family of solutions, not all of which are complete, but some are.

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The most promising candidate to date is the subset $S \subset K(\mathfrak{h})$ that consists of the curvatures that have nontrivial H -stabilizers. It is not a smooth manifold, but it can be stratified into smooth pieces according to the stabilizer type, and these can be analyzed.

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This is the project that I have been engaged in.

Table: Stabilized curvatures for subgroups of $SU(3)$ and Generality

G	$\dim(K(\mathfrak{su}(3)))^G$	G -splitting of \mathbb{C}^3	Generality
$U(2)$	1	$\mathbb{C} \oplus \mathbb{C}^2$	1 const. (known)
$SU(2)$	1	$\mathbb{R} \oplus \mathbb{R} \oplus \mathbb{C}^2$	1 const. (known)
$SO(3)$	1	$\mathbb{R}^3 \oplus \mathbb{R}^3$	does not exist
T^2	3	$\mathbb{C} \oplus \mathbb{C} \oplus \mathbb{C}$	8 constants
$S^1(p/q)^\dagger$	3	$\mathbb{C} \oplus \mathbb{C} \oplus \mathbb{C}$	8 constants
$S^1(0)$	5	$\mathbb{R} \oplus \mathbb{R} \oplus \mathbb{C} \oplus \mathbb{C}$	$s_1 = 2$??
$S^1(1)$	7	$\mathbb{C} \oplus \mathbb{C} \oplus \mathbb{C}$	$s_1 = 4$??

† $p/q \neq 0, 1$, where $S^1(p/q)$ is the circle of diagonal matrices $\text{diag}(e^{ipt}, e^{iqt}, e^{-i(p+q)t})$.

Table: Stabilized curvatures of subgroups of G_2

G	$\dim(K(\mathfrak{g}_2))^G$	G -splitting of \mathbb{R}^7	Generality
$SU(3)$	0	$\mathbb{R}^1 \oplus \mathbb{C}^3$	only flat
$SO(4)$	1	$\mathbb{R}^3 \oplus \mathbb{R}^4$	only $\Lambda_+^2(S^4)$
$U(2)_1$	2	$\mathbb{R}^3 \oplus \mathbb{R}^4$	only $\Lambda_+^2(\mathbb{C}\mathbb{P}^2)$
$U(2)_2$	2	$\mathbb{R}^1 \oplus \mathbb{R}^2 \oplus \mathbb{R}^4$	DNE
\mathbb{T}^2	5	$\mathbb{R} \oplus \mathbb{C} \oplus \mathbb{C} \oplus \mathbb{C}$	'only' consts.
$SU(2)_1$	3	$\mathbb{R} \oplus \mathbb{R} \oplus \mathbb{R} \oplus \mathbb{C}^2$	$s_2 = 0$
$SU(2)_2$	6	$\mathbb{R}^3 \oplus \mathbb{R}^4$???
$SO(3)_1$	1	$\mathbb{R} \oplus \mathbb{R}^3 \oplus \mathbb{R}^3$	DNE
$SO(3)_2$	1	\mathbb{R}^7	'only' consts.
$S^1(p/q)^\dagger$	5	$\mathbb{R} \oplus \mathbb{C} \oplus \mathbb{C} \oplus \mathbb{C}$	'only' consts.
$S^1(1/2)$	7	$\mathbb{R} \oplus \mathbb{C} \oplus \mathbb{C} \oplus \mathbb{C}$	$s_1 = 2$??
$S^1(1)$	9	$\mathbb{R} \oplus \mathbb{C} \oplus \mathbb{C} \oplus \mathbb{C}$	$s_1 = 4$??
$S^1(0)$	13	$\mathbb{R} \oplus \mathbb{R} \oplus \mathbb{R} \oplus \mathbb{C} \oplus \mathbb{C}$???

$^\dagger p/q \neq 0, \frac{1}{2}, 1$

Part II: Second order associative 3-folds

Associative submanifolds $M^3 \subset \mathbb{R}^n$ can be defined by the condition that their tangent spaces belong to the 8-dimensional *associative Grassmannian*

$$\text{Assoc} (\simeq G_2/\text{SO}(4)) = G_2 \cdot \mathbb{R}^3 \subset \text{Gr}_3^+(\mathbb{R}^7).$$

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one can speak of **Σ -manifolds** $M^m \subset \mathbb{R}^n$, whose tangent spaces belong to Σ . The **Gauss map** $\gamma_M : M \rightarrow \Sigma$ given by $\gamma_M(x) = T_x M \in \Sigma$ has a derivative

$$\gamma'_M(x) : T_x M \rightarrow T_{\gamma_M(x)} \Sigma \subset N_{\gamma_M(x)} \otimes T_x^* M \simeq \mathbb{R}^{n-m} \otimes (\mathbb{R}^m)^*$$

that satisfies (because of symmetry of second partials),

$$\mathbb{I}_x = \gamma'_M(x) \in T_{\gamma_M(x)} \Sigma \otimes T_x^* M \cap (N_{\gamma_M(x)} \otimes S^2(T_x^* M)).$$

All of the spaces \mathbb{R}^m , $(\mathbb{R}^m)^\perp = \mathbb{R}^{n-m}$, and $T_{\mathbb{R}^m}\Sigma \simeq \mathfrak{g}/\mathfrak{h}$ are H -modules, and so is the space

$$\mathbb{I}(\mathfrak{g}, \mathfrak{h}) = (T_{\mathbb{R}^m}\Sigma \otimes \mathbb{R}^m) \cap ((\mathbb{R}^m)^\perp \otimes \mathcal{S}^2(\mathbb{R}^m)),$$

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My student, **Marianty Lonel**, did a similar analysis of the case $m = 4$ in 2002 and also found many integrable cases.

Associative 3-folds: $G = G_2$, $H = \mathrm{SO}(4)$. ($\mathrm{Spin}(4) = \mathrm{Sp}(1) \times \mathrm{Sp}(1)$.)

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One can interpret a second fundamental form of an associative 3-manifold (up to real scalar multiples) as a degree ≤ 5 rational mapping

$$P : \mathbb{C}\mathbb{P}^1 \rightarrow \mathbb{C}\mathbb{P}^1, \quad P(z_1, z_2) = [p(z_1, z_2), \overline{p(-\bar{z}_2, \bar{z}_1)}].$$

up to (independent) isometric rotations in the domain and range 2-spheres.

By comparison, for **co-associative submanifolds** $M^4 \subset \mathbb{R}^7$, the coassociative Grassmannian is also $G_2/SO(4) \subset \text{Gr}_4^+(\mathbb{R}^7)$, so again,

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For **Cayley submanifolds** $M^4 \subset \mathbb{R}^8$, the Cayley Grassmannian is $\text{Spin}(7)/H \subset \text{Gr}_4^+(\mathbb{R}^8)$, where $H = (\text{Sp}(1) \times \text{Sp}(1) \times \text{Sp}(1))/\mathbb{Z}_2$. Then

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while the second fundamental form space turns out to be

$$\mathbb{I}(\mathfrak{g}, \mathfrak{h}) = V_{2,3,1}^{\mathbb{R}} \simeq \mathbb{R}^{24},$$

The classification of the stabilizer types in the associative case can now be worked out.

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Proposition 0: If $p(z_1, z_2)$ represents an associative second fundamental form with nontrivial stabilizer in $H = \text{SO}(4)$, then p is in the orbit of one of the following types (where a, b, u, v are real)

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(N.B. There are some inequalities among a, b, u, v in the above cases in order to ensure no larger symmetry. Also, the three circles in Cases 1–3 are not conjugate in $\text{SO}(4)$.)

Proposition 1: The associative 3-folds in \mathbb{R}^7 whose second fundamental forms have type $p = a z_1^5$

- are all ruled,
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Remark: The ruled associative 3-folds in \mathbb{R}^7 can be regarded as surfaces in $\Lambda(\mathbb{R}^7) \simeq TS^6$, the space of lines in \mathbb{R}^7 . There is a unique almost complex structure on $\Lambda(\mathbb{R}^7)$ such that these surfaces are the pseudoholomorphic curves in $\Lambda(\mathbb{R}^7)$. Thus, they locally depend on $s_1 = 12$ functions of 1 variable.

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Proposition 4: (\mathbb{Z}_4) The only associative 3-folds in \mathbb{R}^7 whose second fundamental forms have type $p = a z_1^5 + 5b z_1 z_2^4$ must actually have either $a = 0$ or $b = 0$ (and so have continuous symmetry).

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Proposition 6: (\mathbb{Z}_2) In progress.